

Introduction





Major challenge of vehicle-based ReID

Intra-class variability > inter-class variability

Contributions

- <u>City scale</u>: 40 cameras over 10 intersections \bullet
- MTMC vehicle tracking: Videos and camera topology available
- Baselines: ReID, MTSC track., detection & spatio-temporal assoc.

Related Benchmarks

		Benchmark	# cameras	# boxes	# boxes/ID	Video	Geom.	Multiview
person	ReID	Market1501 [59]	6	32,668	30.8	×	×	\checkmark
		DukeMTMC-reID [35, 63]	8	36,411	20.1	×	×	\checkmark
		MSMT17 [47]	15	126,441	21.8	×	×	\checkmark
		CUHK03 [23]	2	13,164	19.3	×	×	×
		CUHK01 [22]	2	3,884	4.0	×	×	×
		VIPeR [12]	2	1,264	2.0	×	×	×
		PRID [15]	2	1,134	1.2	×	×	×
		CAVIAR [9]	2	610	8.5	×	×	×
	MTMC	MARS [58]	6	1,191,003	944.5	×	×	\checkmark
		DukeMTMC [35, 53]	8	4,077,132	571.2	\checkmark	\checkmark	\checkmark
		NLPR_MCT [8]	12	36,411	65.8	\checkmark	\checkmark	\checkmark
		VeRi-776 [29]	20	49,357	63.6	×	\checkmark	\checkmark
le	D ₂ ID	VehicleID [27]	2	221,763	8.4	×	×	×
hic	KeiD	PKU-VD1 [55]	-	846,358	6.0	×	×	×
Ve		PKU-VD2 [55]	-	807,260	10.1	×	×	×
	MTMC	CityFlow (proposed)	40	229,680	344.9	\checkmark	\checkmark	\checkmark

CityFlow: A City-Scale Benchmark For Multi-Target Multi-Camera Vehicle Tracking And Re-Identification Zheng Tang, Milind Naphade, Ming-Yu Liu, Xiaodong Yang, Stan Birchfield, Shuo Wang, Ratnesh Kumar, David Anastasiu and Jeng-Neng Hwang Datasets and evaluation server available at the AI City Challenge Workshop: https://www.aicitychallenge.org/









MTSC tracking & object detection

	3.0						MTSC tracking:
Method	IDF1	Recall	FAR	MT	MOTA	MOTP	DS: DeepSORT
DS+YOLO	78.9%	67.6%	8.6	778	67.4%	65.8%	<u>MO</u> : MOANA
DS+SSD	79.5%	69.2%	8.3	756	68.9%	65.5%	Object detection:
DS+FRCNN	78.9%	66.9%	15.3	761	66.7%	65.5%	<u>YOLO</u> : YOLOv3
TC+YOLO	79.1%	68.1%	8.5	871	68.0%	66.0%	<u>SSD</u> : SSD512
TC+SSD	79.7%	70.4%	7.4	895	70.3%	65.6%	FRCNN: Faster R-CNN
TC+FRCNN	78.7%	68.5%	12.0	957	68.4%	65.9%	Spatio-temporal assoc.:
MO+YOLO	77.8%	69.0%	8.5	965	68.6%	66.0%	PROVID: Spatio-temporal-
MO+SSD	72.8%	68.0%	6.3	980	67.0%	65.9%	based re-ranking
MO+FRCNN	75.6%	69.5%	10.8	1094	68.6%	66.0%	<u>2VVGIVIIVIF</u> : Learning
							<u>FVS</u> : Manually set
MTMC trac	ckina						transition distributions

Spatio-temporal	MTSC tracking	Image-based ReID						
association		FVS_Bh.	Xent	Htri	Cent	Xent+Htri	BA	BS
PROVID [29]	DeepSORT [50]	21.5%	31.3%	35.3%	27.6%	34.5%	35.6%	33.6%
	TC [43]	22.1%	35.2%	39.4%	32.7%	39.9%	40.6%	39.0%
	MOANA [40]	21.7%	29.1%	33.0%	26.1%	31.9%	34.4%	31.8%
2WGMMF [20]	DeepSORT [50]	25.0%	35.3%	38.4%	31.2%	37.5%	40.3%	39.8%
	TC [43]	27.6%	39.5%	41.7%	34.7%	43.3%	44.1%	45.1%
	MOANA [40]	20.2%	32.2%	35.9%	28.2%	36.5%	38.1%	37.7%
FVS [43]	DeepSORT [50]	24.9%	36.4%	40.0%	30.8%	39.0%	41.3%	41.4%
	TC [43]	27.6%	40.5%	42.7%	36.6%	42.4%	46.3%	46.0%
	MOANA [40]	21.2%	32.7%	36.4%	29.2%	37.5%	39.5%	36.9%

AI City Challenge Workshop @ CVPR 2019

Track	Winner	Runner-up
MTMC tracking	U. Washington	DiDi Global
Vehicle ReID	Baidu ZeroOne	U. Washington



LONG BEACH **CALIFORNIA** June 16-20, 2019

Track 1 (MTMC tracking) & Track 2 (ReID) based on CityFlow > Online evaluation server with public leader board provided > 334 participating teams from 44 countries around the world

